1. Python

from numpy import array

from scipy.linalg import solve

import numpy as np

def gaussElimination(A,b):

#A = array([[4,-2,1],[-2,4,-2],[1,-2,4]])

#b = array([11,-16,17])

x = solve(A, b)

print("X1,X2,X3 =",x)

check = np.dot(A, x) - b

#print("A\*x-b harus [0 0 0]")

#print("A\*x-b = ", check)

return x,check

A = array([[1, -2, 1, -3, 1], [2, 1, -3, 1, 2], [-1, -1, -1, -1, -1], [1, 1, 1, -1, -1], [2, -2, 1, -1, 1]])

b = array([1, 15, -3, -1, 0])

x, check = gaussElimination(A, b)

jawaban :

X1,X2,X3,X4,X5 = [ 1. 2. -2. -1. 3.]

1. Python

import numpy as np

from pypoly import Polynomial

def chunkIt(seq, num):

avg = len(seq) / float(num)

out = []

last = 0.0

while last < len(seq):

out.append(seq[int(last):int(last + avg)])

last += avg

return out

def product(list):

p = 1

for i in list:

p \*= i

return p

def Lagrange(x,X):

T = np.zeros((2,len(X)))

list = []

for i in range(len(X)):

for j in range(len(X)):

if i != j:

list.append((x-X[j][0])/(X[i][0]-X[j][0]))

p = []

for i in chunkIt(list,len(X)):

p.append(product(i))

for i in range(len(X)):

T[0][i] = p[i]

T[1][i] = X[i][1]

list2 = []

for i in range(len(X)):

list2.append(T[0][i]\*T[1][i])

return sum(list2)

# Input

# x kecil buat mau dicari nilai brpa

# X gede [x,y]

#Change HERE

x, X = 0.5, [[-1.2, -5.5],[0.3, -5.39],[1.1, -3.4],[1.4, -2.3]] #x,Y

order = len(X)

equations = np.array([[point[0] \*\* i for i in range(order)] for point in X])

values = np.array([point[1] for point in X])

coefficients = np.linalg.solve(equations, values)

print ('coefficients', list(coefficients))

p = Polynomial(\*coefficients)

print(p)

print(p(x))

**Jawaban :**

coefficients [-5.786468227424749, 1.006411776629166, 1.0479198337893987, 0.008589236850107639]

-5.78647 + 1.00641 \* X + 1.04792 \* X\*\*2 + 0.00858924 \* X\*\*3

-5.020208726056554

1. Python

def func( x ):

#CHANGE HERE

return x\*\*5 - 4\*x\*\*4 + 2\*x\*\*3 + x\*\*2 - x +10

# Derivative of the above function

# which is 3\*x^x - 2\*x

def derivFunc( x ):

#MANNUAL DERIVATIVE THEN TYPE HERE

return 5\*x\*\*4 - 16\*x\*\*3 + 6\*x\*\*2 + 2\*x -1

# Function to find the root

def newtonRaphson( x ):

h = func(x) / derivFunc(x)

while abs(h) >= 0.0001:

h = func(x)/derivFunc(x)

# x(i+1) = x(i) - f(x) / f'(x)

x = x - h

print("The value of the root is : ", "%.4f"% x)

# Driver program to test above

x0 = 1 # Initial values assumed

newtonRaphson(x0)

**Jawaban :**

The value of the root is : 3.2190

1. Python
2. Python

def f(x):

y = x\*\*4 + x\*\*3 + 2\*x\*\*2 - 3\*x + 10#Insert equation here

return y

#Differential eq

def actual\_diff\_f(x):

y = 4\*x\*\*3 + 3\*x\*\*2 + 4\*x - 3#insert differential equation here

return y

#Forward

def f\_Forward(x,h):

fh = f(x+h)

fx = f(x)

eq = (fh-fx)/h

return eq

#Backward

def f\_Backward(x,h):

fh = f(x-h)

fx = f(x)

eq = (fx-fh)/h

return eq

#Middle

def f\_Middle(x,h):

fh = f(x+h)

fx = f(x-h)

eq = (fh-fx)/(2\*h)

return eq

#Data

x=1.7

h=0.02

Forward = f\_Forward(x,h)

print("using forward method, predicted f'(x):",Forward)

Backward = f\_Backward(x,h)

print("using backward method, predicted f'(x):",Backward)

Middle = f\_Middle(x,h)

print("using backward method, predicted f'(x):",Middle)

Actual = actual\_diff\_f(x)

print("actual f'(x):",Actual)

**Hasil :**

using forward method, predicted f'(x): 32.613928000000136

using backward method, predicted f'(x): 31.636311999999833

using backward method, predicted f'(x): 32.12511999999998

actual f'(x): 32.12199999999999